

Fluctuations of symmetric exclusion with open boundary

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Outline of the mini-course:

- ♣ We will analyse the fluctuations for an exclusion process in contact with stochastic reservoirs when jumps are:
 - ♣ Hydrodynamics (Lecture 1);
 - ♣ Fluctuations (Lecture 2).

Let us start with the simplest case: jumps to nearest-neighbors.

Now $\Lambda = [0, 1]$ and $\Lambda_N = \{1, \dots, N - 1\}$. The state space of the Markov process is $\Omega_N = \{0, 1\}^{\Lambda_N}$.

Lecture **1: Hydrodynamics**

SSEP in contact with reservoirs



The dynamics:

- For $N \geq 1$ let $\Lambda_N = \{1, \dots, N-1\}$.
- We denote the process by $\{\eta_t : t \geq 0\}$ which has state space $\Omega_N := \{0, 1\}^{\Lambda_N}$.
- The infinitesimal generator $\mathcal{L}_N = \mathcal{L}_{N,0} + \mathcal{L}_{N,b}$ is given on $f : \Omega_N \rightarrow \mathbb{R}$, by

$$(\mathcal{L}_{N,0}f)(\eta) = \sum_{x=1}^{N-2} \frac{1}{2} \left(f(\eta^{x,x+1}) - f(\eta) \right),$$

$$(\mathcal{L}_{N,b}f)(\eta) = \frac{\kappa}{N^\theta} \sum_{x \in \{1, N-1\}} c_{r_x}(\eta(x)) \left(f(\eta^x) - f(\eta) \right),$$

where for $x = 1$ and $x = N-1$,

$c_{r_x}(\eta(x)) = r_x(1 - \eta(x)) + (1 - r_x)\eta(x)$, $r_1 = \alpha$ and $r_{N-1} = \beta$.

Goal: analyse the impact of changing the strength of the reservoirs (by changing θ) on the macroscopic behavior of the system.

Invariant measures:

If $\alpha = \beta = \rho$ the Bernoulli product measures are invariant (equilibrium measures): $\nu_\rho(\eta : \eta(x) = 1) = \rho$.

If $\alpha \neq \beta$ the Bernoulli product measure is no longer invariant, but since we have a finite state irreducible Markov process there exists a UNIQUE invariant measure: the stationary measure (non-equilibrium) denoted by μ_{ss} .

By the matrix ansatz method one can get information about this measure. (Not in the long jumps case.)

Hydrodynamic Limit:

♣ For $\eta \in \Omega_N$, let

$$\pi_t^N(\eta, dq) = \frac{1}{N-1} \sum_{x=1}^{N-1} \eta_{tN^2}(x) \delta_{x/N}(dq),$$

be the *empirical measure*. (*Diffusive time scaling!*)

♣ **Assumption:** fix $g : [0, 1] \rightarrow [0, 1]$ measurable and a sequence of probability measures $\{\mu_N\}_{N \geq 1}$ such that for every $H \in C([0, 1])$,

$$\frac{1}{N-1} \sum_{x=1}^{N-1} H\left(\frac{x}{N}\right) \eta(x) \xrightarrow{N \rightarrow +\infty} \int_0^1 H(q) g(q) dq,$$

wrt μ_N . (μ_N is associated with $g(\cdot)$)

Hydrodynamic Limit:

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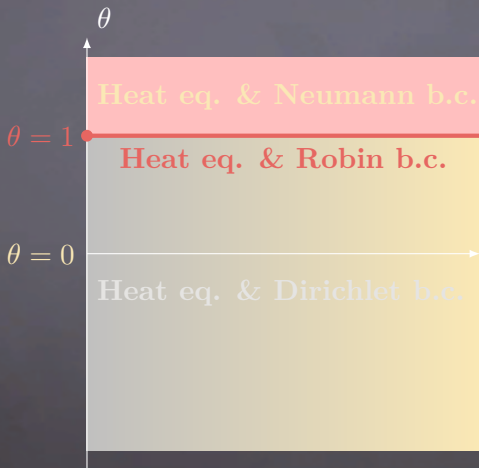
wrt μ_N . (i.e. $\pi_0^N(\eta, dq) \xrightarrow{N \rightarrow +\infty} g(q) dq$)

♣ Then: for any $t > 0$,

$$\pi_t^N(\eta, dq) \xrightarrow{N \rightarrow +\infty} \rho(t, q) dq,$$

wrt $\mu_N(t)$, where $\rho(t, q)$ evolves according to a PDE, the hydrodynamic equation.

Hydrodynamic eq. (Baldasso et al):



Heat equation:

$$\partial_t \rho_t(q) = \frac{1}{2} \partial_q^2 \rho_t(q).$$

♣ $\theta > 1$ Neumann b.c.:

$$\partial_q \rho_t(0) = \partial_q \rho_t(1) = 0.$$

♣ $\theta = 1$ Robin b.c.:

$$\partial_q \rho_t(0) = \kappa(\rho_t(0) - \alpha),$$

$$\partial_q \rho_t(1) = \kappa(\beta - \rho_t(1)).$$

♣ $\theta < 1$ Dirichlet b.c.:

$$\rho_t(0) = \alpha, \rho_t(1) = \beta.$$

Hydrostatic Limit:



Theorem: Let μ_{ss} be the stationary measure for the process $\{\eta_t\}_{t \geq 0}$. Then, μ_{ss} is associated to $\bar{\rho} : [0, 1] \rightarrow [0, 1]$ given on $q \in (0, 1)$ by

$$\bar{\rho}(q) = \begin{cases} (\beta - \alpha)q + \alpha; & \theta < 1, \\ \frac{\kappa(\beta - \alpha)}{2 + \kappa}q + \alpha + \frac{\beta - \alpha}{2 + \kappa}; & \theta = 1, \\ \frac{\beta + \alpha}{2}; & \theta > 1. \end{cases}$$

$\bar{\rho}(\cdot)$ is a stationary solution of the hydrodynamic equation.

The proof:

Proof of the results?

Two things to do:

- ♣ Tightness of \mathbb{Q}_N , where \mathbb{Q}_N is induced by \mathbb{P}_{μ_N} and the map

$$\pi_{\cdot}^N : \mathcal{D}([0, T], \Omega_N) \longrightarrow \mathcal{D}([0, T], \mathcal{M}_+)$$

- ♣ Characterization of limit points: limit points are concentrated on trajectories of measures that are absolutely continuous wrt the Lebesgue measure and the density is a weak solution of the corresponding PDE:

$$\mathbb{Q}(\pi_{\cdot} : \pi_t(dq) = \rho(t, q)dq \text{ and } \rho_t(q) \text{ is solution to the PDE}) = 1.$$

Let us focus on last item.

The notion of weak solution:

Let $g : [0, 1] \rightarrow [0, 1]$ be a measurable function. We say that $\rho : [0, T] \times [0, 1] \rightarrow [0, 1]$ is a weak solution of the HEDBC if:

♣ $\rho \in L^2(0, T; \mathcal{H}^1)$;

♣ ρ satisfies the weak formulation:

$$\begin{aligned} & \int_0^1 \rho_t(q) H_t(q) - g(q) H_0(q) dq \\ & - \int_0^t \int_0^1 \rho_s(q) \left(\frac{1}{2} \partial_q^2 + \partial_s \right) H_s(q) ds dq \\ & + \frac{1}{2} \int_0^t \beta \partial_q H_s(1) - \alpha \partial_q H_s(0) ds = 0, \end{aligned}$$

for all $t \in [0, T]$ and any function $H \in C_0^{1,2}([0, T] \times [0, 1])$.

Another notion of solution:

Let $g : [0, 1] \rightarrow [0, 1]$ be a measurable function. We say that $\rho : [0, T] \times [0, 1] \rightarrow [0, 1]$ is a weak solution of the HEDBC if:

♣ $\rho \in L^2(0, T; \mathcal{H}^1);$

♣ ρ satisfies the weak formulation:

$$\begin{aligned} & \int_0^1 \rho_t(q) H_t(q) dq - \int_0^1 g(q) H_0(q) dq \\ & - \int_0^t \int_0^1 \rho_s(q) \left(\frac{1}{2} \partial_q^2 + \partial_s \right) H_s(q) ds dq = 0, \end{aligned}$$

for all $t \in [0, T]$ and any function $H \in C_c^{1,2}([0, T] \times [0, 1]);$

♣ $\rho_t(0) = \alpha$ and $\rho_t(1) = \beta$, for $t \in (0, T]$.

The notion of weak solution:

Let $g : [0, 1] \rightarrow [0, 1]$ be a measurable function. We say that $\rho : [0, T] \times [0, 1] \rightarrow [0, 1]$ is a weak solution of the heat equation with Robin b.c. if:

♣ $\rho \in L^2(0, T; \mathcal{H}^1),$

♣ ρ satisfies the weak formulation:

$$\begin{aligned} & \int_0^1 \rho_t(q) H_t(q) dq - \int_0^1 g(q) H_0(q) dq \\ & - \int_0^t \int_0^1 \rho_s(q) \left(\frac{1}{2} \partial_q^2 + \partial_s \right) H_s(q) ds dq \\ & + \frac{1}{2} \int_0^t \{ \rho_s(1) \partial_q H_s(1) - \rho_s(0) \partial_q H_s(0) \} ds \\ & - \frac{\kappa}{2} \int_0^t \{ H_s(0) (\alpha - \rho_s(0)) + H_s(1) (\beta - \rho_s(1)) \} ds = 0, \end{aligned}$$

for all $t \in [0, T]$ and any function $H \in C^{1,2}([0, T] \times [0, 1]).$

Characterizing limit points:



Dynkin's formula: Let $\{\eta_t\}_{t \geq 0}$ be a Markov process with generator \mathcal{L} and with countable state space E . Let $F : \mathbb{R}^+ \times E \rightarrow \mathbb{R}$ be a bounded function such that

- $\forall \eta \in E, F(\cdot, \eta) \in C^2(\mathbb{R}^+)$,
- there exists a finite constant C , such that $\sup_{(s, \eta)} |\partial_s^j F(s, \eta)| \leq C$, for $j = 1, 2$.

For $t \geq 0$, let

$$M_t^F = F(t, \eta_t) - F(0, \eta_0) - \int_0^t (\partial_s + \mathcal{L})F(s, \eta_s) ds.$$

Then, $\{M_t^F\}_{t \geq 0}$ is a martingale wrt $\mathcal{F}_s = \sigma(\eta_s; s \leq t)$.

Characterizing limit points:

Let us fix a test function $H : [0, 1] \rightarrow \mathbb{R}$ and apply Dynkin's formula with

$$F(t, \eta_t) = \langle \pi_t^N, H \rangle = \frac{1}{N-1} \sum_{x=1}^{N-1} \eta_{tN^2}(x) H\left(\frac{x}{N}\right).$$

Note that F does not depend on time only through the process η . A simple computation shows that

$$\begin{aligned} N^2 \mathcal{L}_N \langle \pi_s^N, H \rangle &= \langle \pi_s^N, \frac{1}{2} \Delta_N H \rangle \\ &+ \frac{1}{2} \nabla_N^+ H(0) \eta_{sN^2}(1) - \frac{1}{2} \nabla_N^- H(1) \eta_{sN^2}(N-1) \\ &+ \kappa N^{1-\theta} H\left(\frac{1}{N}\right) (\alpha - \eta_{sN^2}(1)) \\ &+ \kappa N^{1-\theta} H\left(\frac{N-1}{N}\right) (\beta - \eta_{sN^2}(N-1)) \end{aligned}$$

$$\underline{\theta \in [0, 1):}$$

Take a function $H : [0, 1] \rightarrow \mathbb{R}$ such that $H(0) = H(1) = 0$ and then we get

$$\begin{aligned} M_t^N(H) &= \langle \pi_t^N, H \rangle - \langle \pi_0^N, H \rangle - \int_0^t \langle \pi_s^N, \frac{1}{2} \Delta_N H \rangle ds \\ &\quad - \frac{1}{2} \int_0^t \nabla_N^+ H(0) \eta_{sN^2}(1) - \nabla_N^- H(1) \eta_{sN^2}(N-1) ds + O(N^{-\theta}). \end{aligned}$$

If we can replace $\eta_{sN^2}(1)$ by α and $\eta_{sN^2}(N-1)$ by β (this will be made rigorous ahead but only works for $\theta < 1$!) then above we have

$$\begin{aligned} M_t^N(H) &= \langle \pi_t^N, H \rangle - \langle \pi_0^N, H \rangle - \int_0^t \langle \pi_s^N, \frac{1}{2} \Delta_N H \rangle ds \\ &\quad - \frac{1}{2} \int_0^t \nabla_N^+ H(0) \alpha - \nabla_N^- H(1) \beta ds + O(N^{-\theta}). \end{aligned}$$

Compare with the PDE (note that H does not depend on time).

Still $\theta \in [0, 1)$:

Take the expectation above to get

$$\begin{aligned} & \frac{1}{N} \sum_{x=1}^{N-1} H\left(\frac{x}{N}\right) \left(\rho_t^N(x) - \rho_0^N(x) \right) - \int_0^t \frac{1}{N} \sum_{x=1}^{N-1} \frac{1}{2} \Delta_N H\left(\frac{x}{N}\right) \rho_s^N(x) ds \\ & - \frac{1}{2} \int_0^t \nabla_N^+ H(0) \alpha - \nabla_N^- H(1) \beta ds + O(N^{-\theta}) = 0. \end{aligned}$$

Assume that $\rho_t^N(x) \sim \rho_t(x/N)$ and take the limit in N to get

$$\begin{aligned} & \int_0^1 \rho_t(q) H(q) - \rho_0(q) H(q) dq - \int_0^t \int_0^1 \frac{1}{2} \partial_q^2 H(q) \rho_s(q) dq ds \\ & - \frac{1}{2} \int_0^t \partial_q H(0) \alpha - \partial_q H(1) \beta ds = 0 \end{aligned}$$

Compare with the PDE (note that H does not depend on time).

$$\underline{\theta < 0:}$$

Recall that the previous error blows up when $N \rightarrow \infty$. So now, we take a function $H : [0, 1] \rightarrow \mathbb{R}$ with compact support and then we get

$$M_t^N(H) = \langle \pi_t^N, H \rangle - \langle \pi_0^N, H \rangle - \int_0^t \langle \pi_s^N, \frac{1}{2} \Delta_N H \rangle ds.$$

Again compare with the PDE but note that H does not depend on time.

In this case we do not see the Dirichlet boundary conditions and we need extra results to conclude.

$$\underline{\theta = 1:}$$

Now, we take a function $H : [0, 1] \rightarrow \mathbb{R}$ and we get

$$\begin{aligned} M_t^N(H) &= \langle \pi_t^N, H \rangle - \langle \pi_0^N, H \rangle - \int_0^t \langle \pi_s^N, \frac{1}{2} \Delta_N H \rangle ds \\ &\quad - \frac{1}{2} \int_0^t \nabla_N^+ H(0) \eta_{sN^2}(1) - \nabla_N^- H(1) \eta_{sN^2}(N-1) ds \\ &\quad - \frac{\kappa}{2} \int_0^t H\left(\frac{1}{N}\right) (\alpha - \eta_{sN^2}(1)) + H\left(\frac{N-1}{N}\right) (\beta - \eta_{sN^2}(N-1)) ds. \end{aligned}$$

If we can replace $\eta_{sN^2}(1)$ (resp. $\eta_{sN^2}(N-1)$) by its average in a box around 1 (resp. $N-1$) (this works for any $\theta \geq 1$):

$$\overrightarrow{\eta}_{sN^2}^{\epsilon N}(1) := \frac{1}{\epsilon N} \sum_{x=1}^{1+\epsilon N} \eta_{sN^2}(x), \quad \overleftarrow{\eta}_{sN^2}^{\epsilon N}(N-1) := \frac{1}{\epsilon N} \sum_{x=N-1}^{N-1-\epsilon N} \eta_{sN^2}(x)$$

and noting that $\overrightarrow{\eta}_{sN^2}^{\epsilon N}(1) \sim \rho_s(0)$ (resp. $\overrightarrow{\eta}_{sN^2}^{\epsilon N}(N-1) \sim \rho_s(1)$) we would get the terms in the PDE (compare).

$$\underline{\theta > 1:}$$

Again we take a function $H : [0, 1] \rightarrow \mathbb{R}$ and in this case the terms from the boundary vanish. So we get

$$\begin{aligned} M_t^N(H) &= \langle \pi_t^N, H \rangle - \langle \pi_0^N, H \rangle - \int_0^t \langle \pi_s^N, \frac{1}{2} \Delta_N H \rangle ds \\ &\quad - \frac{1}{2} \int_0^t \nabla_N^+ H(0) \eta_{sN^2}(1) - \nabla_N^- H(1) \eta_{sN^2}(N-1) ds + O(N^{1-\theta}). \end{aligned}$$

As above, if we can replace $\eta_{sN^2}(1)$ (resp. $\eta_{sN^2}(N-1)$) by its average in a box around 1 (resp. $N-1$) and noting that $\vec{\eta}_{sn^2}^{\epsilon N}(1) \sim \rho_s(0)$ (resp. $\vec{\eta}_{sn^2}^{\epsilon N}(N-1) \sim \rho_s(1)$) we would get the terms in the PDE (compare).

Keystone ingredients:

replacement lemmas

Recall that we need to prove that



For any $t > 0$, we have that:

- for $\theta < 1$

$$\limsup_{N \rightarrow \infty} \mathbb{E}_{\mu_N} \left[\left| \int_0^t (\eta_{sN^2}(1) - \alpha) ds \right| \right] = 0;$$

- for $\theta \geq 1$

$$\limsup_{N \rightarrow \infty} \mathbb{E}_{\mu_N} \left[\left| \int_0^t (\eta_{sN^2}(1) - \vec{\eta}_{sN^2}^{\epsilon N}(1)) ds \right| \right] = 0;$$

and a similar result for $N - 1$.

The empirical profile:

Fix an initial measure μ_N in Ω_N . For $x \in \Lambda_N$ and $t \geq 0$, let

$$\rho_t^N(x) = \mathbb{E}_{\mu_N}[\eta_{tN^2}(x)].$$

We extend this definition to the boundary by setting

$$\rho_t^N(0) = \alpha \text{ and } \rho_t^N(N) = \beta, \text{ for all } t \geq 0.$$

A simple computation shows that $\rho_t^N(\cdot)$ is a solution of

$$\partial_t \rho_t^N(x) = N^2(\mathcal{B}_N \rho_t^N)(x), \quad x \in \Lambda_N, \quad t \geq 0$$

where the operator \mathcal{B}_N acts on functions $f : \Lambda_N \cup \{0, N\} \rightarrow \mathbb{R}$ as

$$\begin{aligned} N^2(\mathcal{B}_N f)(x) &= \Delta_N f(x), \quad \text{for } x \in \{2, \dots, N-2\}, \\ N^2(\mathcal{B}_N f)(1) &= N^2(f(2) - f(1)) + \frac{\kappa N^2}{N^\theta} (f(0) - f(1)), \\ N^2(\mathcal{B}_N f)(N-1) &= N^2(f(N-2) - f(N-1)) + \frac{\kappa N^2}{N^\theta} (f(N) - f(N-1)). \end{aligned}$$

Stationary empirical profile:

The stationary solution of the previous equation is given by

$$\rho_{ss}^N(x) = \mathbb{E}_{\mu_{ss}}[\eta_{tN^2}(x)] = a_N x + b_N$$

where $a_N = \frac{\kappa(\beta-\alpha)}{2N^\theta + \kappa(N-2)}$ and $b_N = a_N(\frac{N^\theta}{\kappa} - 1) + \alpha$, so that

$$\lim_{N \rightarrow \infty} \max_{x \in \Lambda_N} |\rho_{ss}^N(x) - \bar{\rho}(\frac{x}{N})| = 0$$

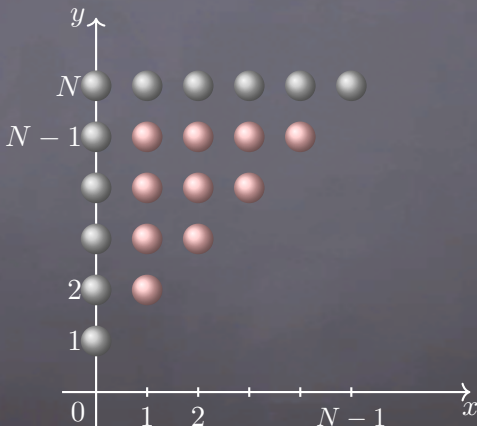
where

$$\bar{\rho}(q) = \begin{cases} (\beta - \alpha)q + \alpha; & \theta < 1, \\ \frac{\kappa(\beta-\alpha)}{2+\kappa}q + \alpha + \frac{\beta-\alpha}{2+\kappa}; & \theta = 1, \\ \frac{\beta+\alpha}{2}; & \theta > 1, \end{cases}$$

is a stationary solution of the hydrodynamic equation.

Stationary correlations:

Let $V_N = \{(x, y) \in \{0, \dots, N\}^2 : 0 < x < y < N\}$, and its boundary $\partial V_N = \{(x, y) \in \{0, \dots, N\}^2 : x = 0 \text{ or } y = N\}$.



Stationary correlations:

For $x < y \in V_N$, let $\varphi_t^N(x, y)$ the two point correlation function between the occupation sites at $x < y \in V_N$ is defined by

$$\varphi_t^N(x, y) = \mathbb{E}_{\mu_N}[(\eta_{tN^2}(x) - \rho_t^N(x))(\eta_{tN^2}(y) - \rho_t^N(y))].$$

Doing some simple, but long, computations we see that φ_t^N is a solution of

$$\begin{cases} \partial_s \varphi_s(x, y) = \Delta_V^N \varphi_s(x, y) + g_s^N(x, y) + f_s^N(x, y), & (x, y) \in V_N, \\ \varphi_s(x, y) = 0, & (x, y) \in \partial V_N, \end{cases}$$

where the discrete laplacian $\Delta_{V_N}^N : V_N \cup \partial V_N \rightarrow \mathbb{R}$ is defined by

$$\begin{cases} (\Delta_V^N f)(x, y) = N^2(f(x+1, y) + f(x-1, y) + f(x, y-1) \\ \quad + f(x, y+1) - 4f(x, y)), & \text{for } |x-y| > 1, \\ (\Delta_V^N f)(x, x+1) = N^2(f(x-1, x+1) + f(x, x+2) - 2f(x, x+1)) \\ (\Delta_V^N f)(x, y) = 0, & \text{if } (x, y) \in \partial V_N. \end{cases}$$

Stationary correlations:

Above

$$\begin{aligned}g_t^N(x, y) &= -(\nabla_N^+ \rho_t^N(x))^2 \delta_{y=x+1}, \\ \nabla_N^+ \rho_t^N(x) &= N(\rho_t^N(x+1) - \rho_t^N(x)) \\ f_s^N(x, y) &= \left(N^2 - \frac{N^2}{N^\theta}\right) \varphi_t^N(x, y) \delta_{\{|y-x|=1, x=1 \text{ or } y=N-1\}}.\end{aligned}$$

From simple, but long, computations we conclude that

$$\varphi_{ss}^N(x, y) = -\frac{(\alpha - \beta)^2(x + N^\theta - 1)(N - y + N^\theta - 1)}{(2N^\theta + N - 2)^2(2N^\theta + N - 3)}. \quad (1)$$

from where it follows that

$$\max_{x < y} |\varphi_{ss}^N(x, y)| = \begin{cases} O\left(\frac{N^\theta}{N^2}\right), & \theta < 1, \\ O\left(\frac{1}{N}\right), & \theta = 1, \\ O\left(\frac{1}{N^\theta}\right), & \theta > 1, \end{cases} \rightarrow_{N \rightarrow \infty} 0. \quad (2)$$